

# Adjustable Precision Shunt Regulator

## FEATURES

- Low voltage operation (1.24V)
- Adjustable output voltage from  $V_O = V_{REF}$  to 12V
- Wide operating current range from  $55\mu A$  to 100mA
- Low dynamic output impedance  $0.25\Omega$  typ.
- ESD rating is 6kV (per MIL-STD 883D)

**Pb-free, RoHS compliant.**

## APPLICATIONS

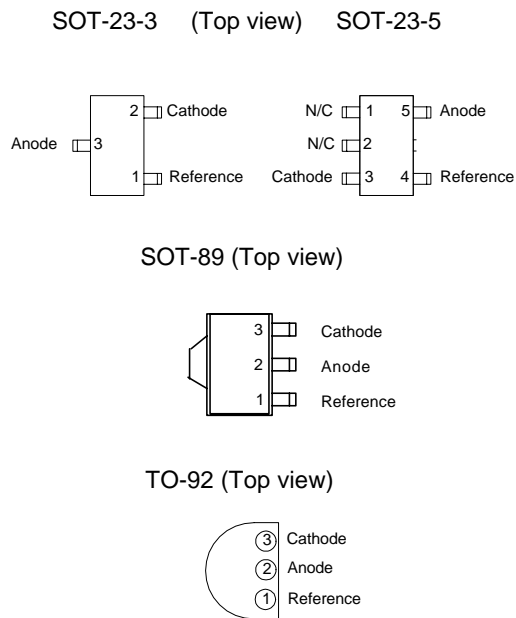
- Linear Regulators
- Adjustable Supplies
- Switching Power Supplies
- Battery Operated Computers
- Instrumentation

## DESCRIPTION

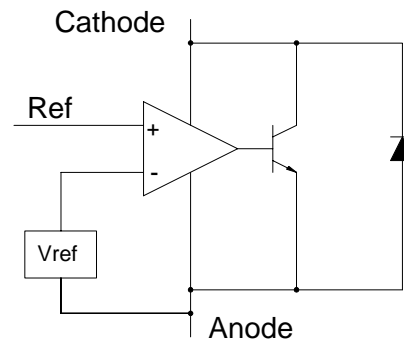
The SS432G is a low-voltage three-terminal adjustable shunt regulator with guaranteed thermal stability over the applicable temperature range. The output voltage can be set to any value between  $V_{REF}$  (approximately 1.24V) and 12V using two external resistors (see application circuit). This device has a typical output impedance of 0.25 ohms. Active output circuitry provides very sharp turn-on characteristics, making this device an excellent alternative to Zener diodes in many applications.

The SS432G is characterized for operation from  $0^{\circ}C$  to  $105^{\circ}C$ , and four package options (SOT-23-3, SOT-23-5, SOT-89, TO-92) allow the designer the opportunity to select the proper package for the application.

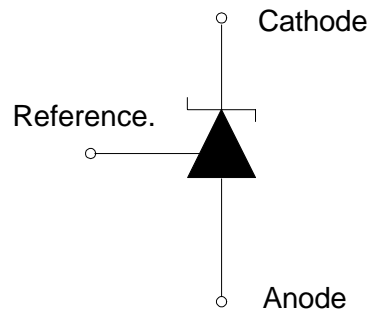
## PIN CONFIGURATION



## BLOCK DIAGRAM



## SYMBOL



## ORDERING INFORMATION

SS432GxB TR

Package type:

- GN = SOT-23-3, RoHS compliant
- GT = TO-92, RoHS compliant
- GG = SOT-89, RoHS compliant
- GV = SOT-23-5, RoHS compliant

Example: SS432GNB TR

-> SS432G in RoHS-compliant SOT-23-3 shipped on tape and reel

**ABSOLUTE MAXIMUM RATINGS over ambient temp. range.**

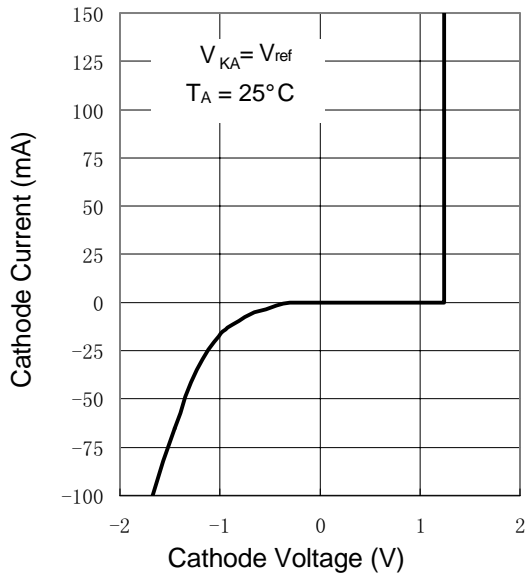
Parameter	Symbol	Maximum	Units
Cathode Voltage	$V_{KA}$	12	V
Continuous Cathode Current	$I_{KA}$	150	mA
Reference Current	$I_{REF}$	3	mA
Operating Junction Temperature	$T_j$	150	°C
Storage Temperature Range	$T_{STG}$	-45 to +150	°C
Thermal Resistance	$\theta_{JA}$	160	°C/W
Lead Temperature (Soldering - std.lead finish)	$T_{LEAD}$	260° C/10 sec.	

**ELECTRICAL CHARACTERISTICS ( $T_A = 25^\circ\text{C}$ )**

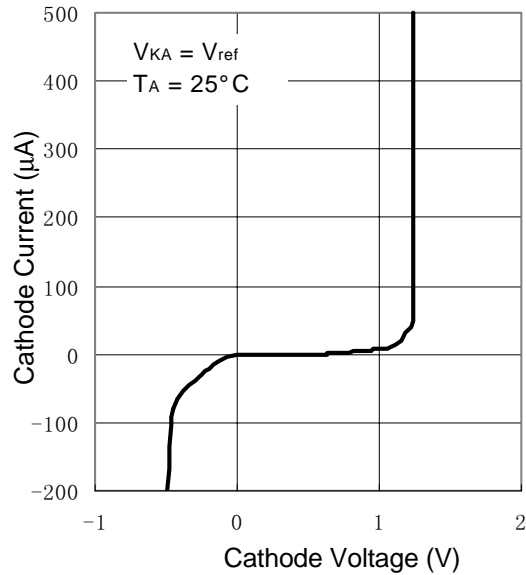
PARAMETER	SYMBOL	TEST CIRCUIT	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Reference voltage 1%	$V_{ref}$	1	$V_{KA} = V_{ref}$ $I_{KA} = 10\text{mA}$	1.228	1.240	1.252	V
Deviation of reference voltage over full temperature range	$V_{I(dev)}$	1	$V_{KA} = V_{ref}$ , $I_{KA} = 10\text{mA}$ $T_A = \text{full range}$		4	12	mV
Ratio of change in reference voltage to the change in cathode voltage	$\frac{\Delta V_{ref}}{\Delta V_{KA}}$	2	$I_{KA} = 10\text{mA}$ , $\Delta V_{KA} = V_{ref}$ to 12V		-1.5	-2.7	mV/V
Reference current	$I_{ref}$	2	$I_{KA} = 10\text{mA}$ , $R1 = 10\text{k}\Omega$ , $R2 = \infty$		0.15	0.5	$\mu\text{A}$
Deviation of reference current over full temperature range	$I_{I(dev)}$	2	$I_{KA} = 10\text{mA}$ , $R1 = 10\text{k}\Omega$ , $R2 = \infty$ $T_A = \text{full range}$		0.05	0.30	$\mu\text{A}$
Minimum cathode current for regulation	$I_{min}$	1	$V_{KA} = V_{ref}$		55	80	$\mu\text{A}$
Off-state cathode current	$I_{off}$	3	$V_{KA} = 12\text{V}$ , $V_{ref} = 0$		0.001	0.1	$\mu\text{A}$
Dynamic impedance	$ Z_{KA} $	1	$I_{KA} = 100\mu\text{A}$ to 100mA, $V_{KA} = V_{ref}$ $f \leq 1\text{kHz}$		0.25	0.4	$\Omega$

TYPICAL PERFORMANCE CHARACTERISTICS

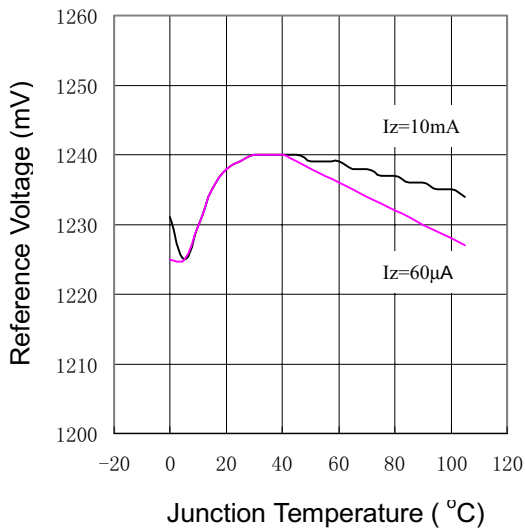
CATHODE CURRENT  
Vs.  
CATHODE VOLTAGE



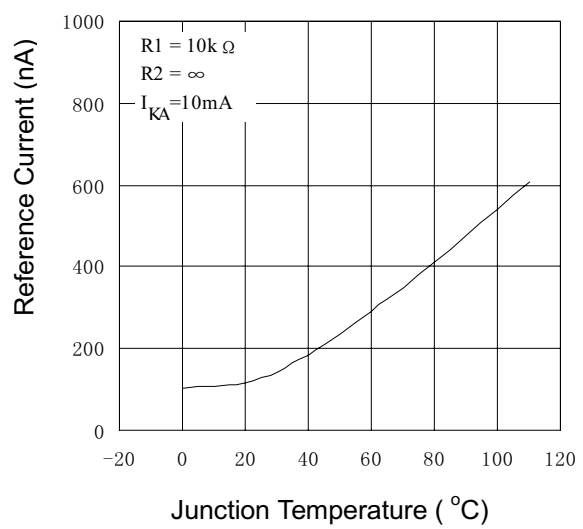
CATHODE CURRENT  
Vs.  
CATHODE VOLTAGE

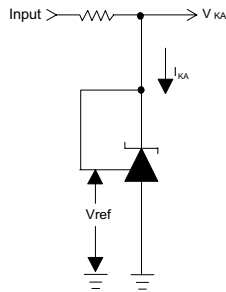


REFERENCE VOLTAGE  
Vs.  
JUNCTION TEMPERATURE

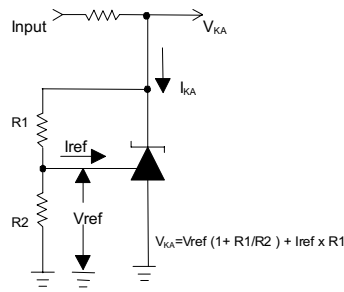


REFERENCE INPUT CURRENT  
Vs.  
JUNCTION TEMPERATURE

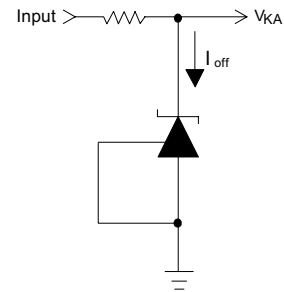


**TEST CIRCUITS**


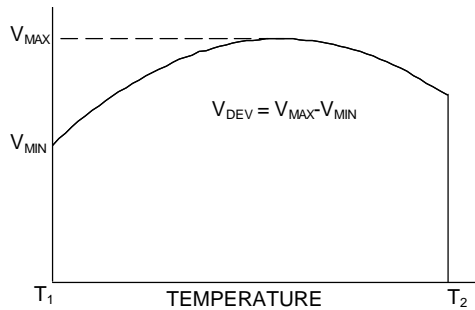
**Test Circuit 1:**  
 $V_{KA} = V_{ref}$



**Test Circuit 2:**  
 $V_{KA} > V_{ref}$



**Test Circuit 3:**  
**Off State Current**

**APPLICATION INFORMATION**


Deviation of reference input voltage,  $V_{DEV}$ , is defined as the maximum variation of the reference input voltage over the full temperature range.

The average temperature coefficient of the reference input voltage,  $\alpha V_{REF}$  is defined as:

$$\Delta V_{REF} \frac{\text{ppm}}{^{\circ}\text{C}} = \frac{\pm \left[ \frac{V_{MAX} - V_{MIN}}{V_{REF}(\text{at } 25^{\circ}\text{C})} \right] 10^6}{T_2 - T_1} = \frac{\pm \left[ \frac{V_{DEV}}{V_{REF}(\text{at } 25^{\circ}\text{C})} \right] 10^6}{T_2 - T_1}$$

Where:

$T_2 - T_1$  = full temperature change.

$\alpha V_{REF}$  can be positive or negative depending on whether the slope is positive or negative.

Example:  $V_{DEV} = 12.0\text{mV}$ ,  $V_{REF} = 1240\text{mV}$ ,

$T_2 - T_1 = 105^{\circ}\text{C}$ , slope is negative.

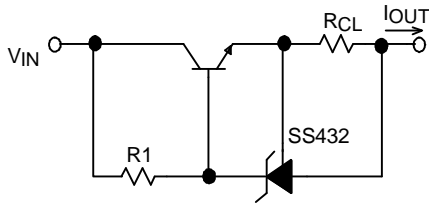
$$aV_{REF} = \frac{\left[ \frac{12.0\text{mV}}{1240\text{mV}} \right] 10^6}{105^{\circ}\text{C}} = -92\text{ppm}/^{\circ}\text{C}$$

**Note 4.** The dynamic output impedance,  $R_Z$ , is defined as:

$$R_Z = \frac{\Delta V_Z}{\Delta I_Z}$$

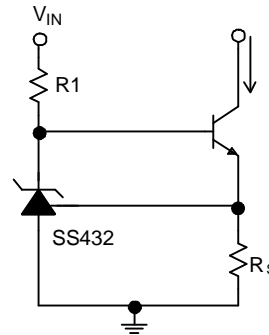
When the device is programmed with two external resistors,  $R_1$  and  $R_2$ , (see Fig. 2), the dynamic output impedance of the overall circuit, is defined as:

$$r_Z = \frac{\Delta V}{\Delta I} \cong R_Z \left[ 1 + \frac{R_1}{R_2} \right]$$

**APPLICATION EXAMPLES**


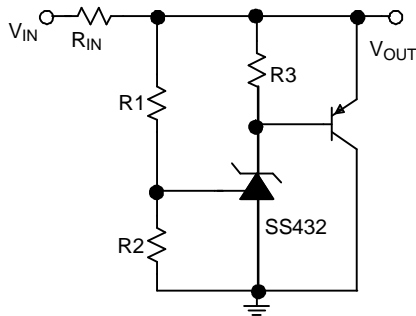
$$I_{OUT} = V_{REF} / R_{CL}$$

Current Limiter or Current Source



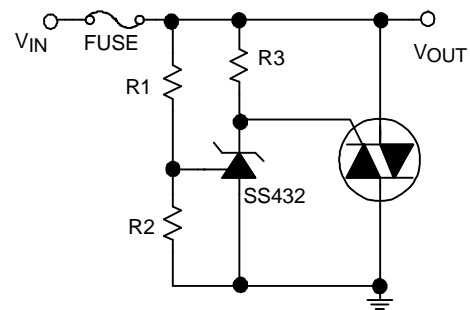
$$I_{OUT} = V_{REF} / R_S$$

Constant-Current Sink



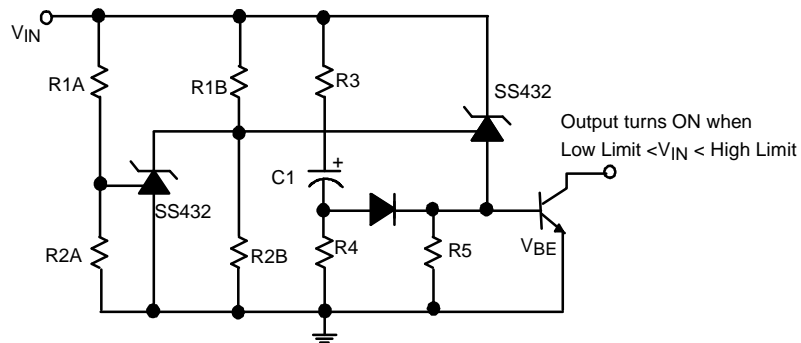
$$V_{OUT} \cong (1 + R_1/R_2) \times V_{REF}$$

Higher Current Shunt Regulator



$$V_{LIMIT} \cong (1 + R_1/R_2) \times V_{REF}$$

Crow Bar

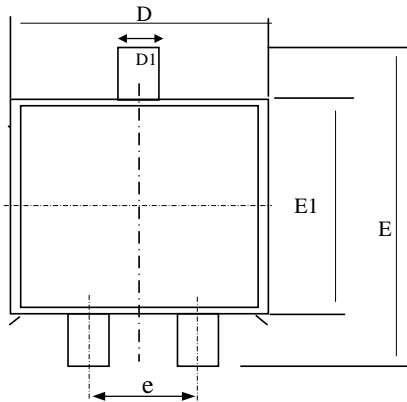


$$\text{Low Limit} \cong V_{REF} (1 + R_{1B}/R_{2B}) + V_{BE}$$

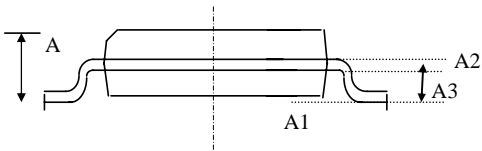
$$\text{High Limit} \cong V_{REF} (1 + R_{1A}/R_{2A})$$

Over-Voltage/Under-Voltage Protection Circuit

 Output turns ON when  
 Low Limit < VIN < High Limit

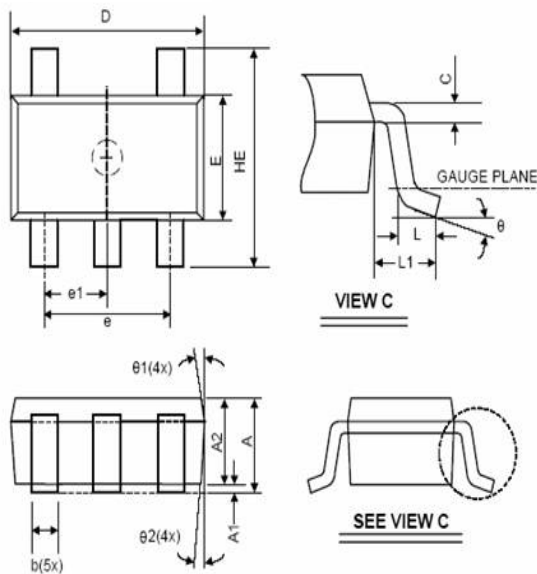
**PHYSICAL DIMENSIONS SOT-23-3**


SYMBOL	MIN	NOM	MAX
A	0.88	1.10	1.30
A1	0.00	----	0.10
D1	0.30	0.40	0.51
e	1.70	2.00	2.30
D	2.80	2.90	3.04
E	2.10	2.50	2.90
E1	1.20	1.40	1.60

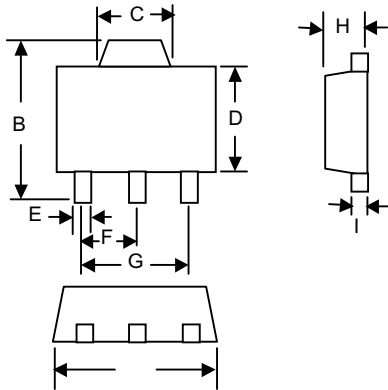


Units : mm

Dimensions do not include mold protrusions.

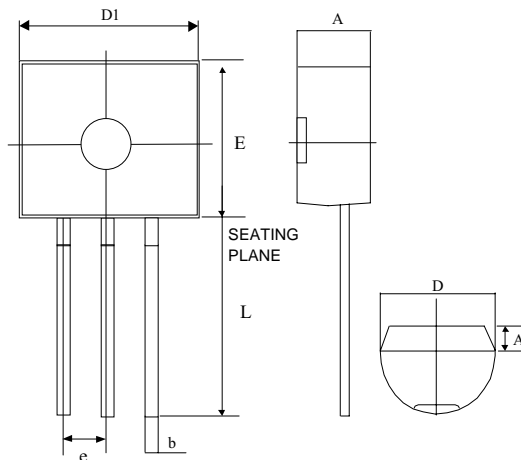
**SOT-23-5**


Symbol	Dimensions In Millimeters			Dimensions In Inches		
	Min.	Nom.	Max.	Min.	Nom.	Max.
A	1.05	-	1.35	0.041	-	0.053
A1	0.05	-	0.15	0.002	-	0.006
A2	1.00	1.10	1.20	0.039	0.043	0.047
b	0.25	-	0.50	0.010	-	0.020
C	0.08	-	0.20	0.003	-	0.008
D	2.70	2.90	3.00	0.106	0.114	0.118
E	1.50	1.60	1.70	0.059	0.063	0.067
HE	2.60	2.80	3.00	0.102	0.110	0.118
L	0.30	-	0.60	0.012	-	0.024
L1	0.50	0.60	0.70	0.020	0.024	0.028
e	1.80	1.90	2.00	0.071	0.075	0.079
e1	0.85	0.95	1.05	0.033	0.037	0.041
theta	0°	5°	10°	0°	5°	10°
theta1	3°	5°	7°	3°	5°	7°
theta2	6°	8°	10°	6°	8°	10°

**PHYSICAL DIMENSIONS SOT-89**


SYMBOL	MIN	MAX
A	4.40	4.60
B	4.05	4.25
C	1.50	1.70
D	2.40	2.60
E	0.31	0.46
F	1.48	1.52
G	2.96	3.04
H	1.40	1.60
I	0.35	0.41

Units: mm.

**PHYSICAL DIMENSIONS TO-92**


Symbol	Min	Nom	Max
A	3.45	3.56	3.66
A1	1.22	1.3	1.37
b	-	0.38	-
D1	4.27	4.52	4.78
D	4.14	4.29	4.45
E	4.32	4.57	4.83
e	-	1.27	-
L	12.98	13.49	14.00

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